

**Ceng 375 Numerical Computing**  
**Midterm**  
**Nov 10, 2010 14.40–16.30**  
**Good Luck!**

1. (10 pts) A three digit, decimal machine which rounds all intermediate calculations, calculates the value of

$$f(x) = x^2 - 6x + 8 \text{ for } x = 1.99 \text{ as } \bar{f}(1.99) = 0.0600$$

What are the forward and backward errors error associated with this calculation?

2. (10 pts) Derive the Newton's method formula using a Taylor series of  $f(x)$ .
3. (20 pts) Use Muller's method to find the root of

$$f(x) = x^3 - x - 2$$

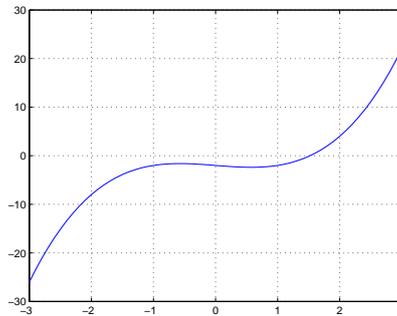


Figure 1: Plot of the function,  $x^3 - x - 2$ .

Start with  $x_2 = 1.0$ ,  $x_0 = 1.2$ , and  $x_1 = 1.4$  and find  $x_3$  and  $x_4$  (two iterations).

```
>> format long
>> x=-3:0.1:3
>> fzero('x.^3-x-2', [-3 3])
ans = 1.521379706804568
```

```

>> x=-3:0.1:3;
>> plot(x,x.^3-x-2);grid on;
>> x2=1.0;
>> x0=1.2;
>> x1=1.4;
>> h2=x0-x2;
>> gamma=h2/h1;
>> fn=inline('x.^3-x-2');
>> c=feval(fn,x0);
>> a=(gamma*feval(fn,x1)-feval(fn,x0)*(1+gamma)+feval(fn,x2))
    /(gamma*h1^2*(1+gamma));
>> b=(feval(fn,x1)-feval(fn,x0)-a*h1^2)/h1;
>> nu=(2*c)/(b+sqrt(b^2-4*a*c));
>> root=x0-nu
%%%
>> x2=1.2;
>> x0=1.4;
>> x1=1.524956139135861;
>> h1=x1-x0;
>> h2=x0-x2;
>> gamma=h2/h1;
>> c=feval(fn,x0);
>> a=(gamma*feval(fn,x1)-feval(fn,x0)*(1+gamma)+feval(fn,x2))
    /(gamma*h1^2*(1+gamma));
>> b=(feval(fn,x1)-feval(fn,x0)-a*h1^2)/h1;
>> nu=(2*c)/(b+sqrt(b^2-4*a*c));
>> root=x0-nu
%%%%
>> x2=1.4;
>> x0=1.521356085625905;;
>> x1=1.524956139135861;
>> h1=x1-x0;
>> h2=x0-x2;
>> gamma=h2/h1;
>> c=feval(fn,x0);
>> a=(gamma*feval(fn,x1)-feval(fn,x0)*(1+gamma)+feval(fn,x2))
    /(gamma*h1^2*(1+gamma));
>> b=(feval(fn,x1)-feval(fn,x0)-a*h1^2)/h1;
>> nu=(2*c)/(b+sqrt(b^2-4*a*c));
>> root=x0-nu
root =
    1.521379705079513

```

4. (30 pts) Consider the function:

$$f(x) = \sin(x) - 4 * x + 2$$

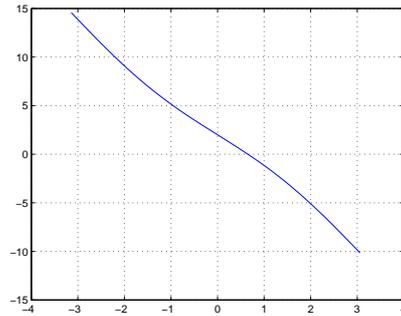


Figure 2: Plot of the function,  $\sin(x) - 4 * x + 2$ .

i Use two iterations of Newton's method to estimate the root of this function between  $x = 0.0$  and  $x = 1.0$  (Use four significant figures)

Newton's method uses the algorithm

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

where, for this function

$$f'(x) = \cos(x) - 4$$

Also, in this case:

$$f(0.0) = 2, \text{ and } f(1.0) = -1.1585$$

```
>> format long
>> x=-pi:0.1:pi
>> fzero('sin(x)-4*x+2',[0 1])
ans = 0.651618523135209
>> x=0;
>> sin(x)-4*x+2
ans = 2
>> x=1;
>> sin(x)-4*x+2
```

```

ans = -1.158529015192103
write the function
function fx=func(x)
fx=sin(x)-4*x+2;
save as func.m
write the function
function fx=funcdiff(x)
fx=cos(x)-4;
save as funcdiff.m

```

The best choice for  $x_0$  is usually the value producing the smallest residual, i.e. in this case

$$x_0 = 0$$

```

>> x0=0;x0-(func(x0)/funcdiff(x0))
ans = 0.6667 (0.666666666666667)
>> x0=0.6667;x0-(func(x0)/funcdiff(x0))
ans = 0.6516 (0.651640263601115)
>> x0=0.6516;x0-(func(x0)/funcdiff(x0))
ans = 0.6516 (0.651618523167672)

```

or start with

$$x_0 = 1$$

```

>> x0=1;x0-(func(x0)/funcdiff(x0))
ans = 0.6651 (0.665135766874333)
>> x0=0.6651;x0-(func(x0)/funcdiff(x0))
ans = 0.6516 (0.651635876939131)
>> x0=0.6516;x0-(func(x0)/funcdiff(x0))
ans = 0.6516 (0.651618523167672)

```

- ii Estimate the error in your answer to part i. To estimate the error, compute one more iteration (third iteration),

$$x_0 = 0$$

$$\begin{aligned}
e_2 = x_3 - x_2 &= (0.651618523167672) - (0.651640263601115) \\
&= -2.174043344305154e - 05
\end{aligned}$$

or start with

$$x_0 = 1$$

$$\begin{aligned}
e_2 = x_3 - x_2 &= (0.651618523167672) - (0.651635876939131) \\
&= -1.735377145906103e - 05
\end{aligned}$$

- iii Approximately how many iterations of the bisection method would have been required to achieve the same error? (Hint: if the value in part ii is negative, take absolute value of it.) The error in the bisection method satisfies

$$e_n = \left| \frac{\text{Original Interval}}{2^n} \right|$$

In this case, taking the original interval to be  $[0, 1]$ , we would have

$$e_n = \left| \frac{1}{2^n} \right|$$

Therefore, to achieve approximately the same error as we obtained with two iteration of Newton's method here, would require sufficient iterations of bisection to ensure

$$\frac{1}{2^n} = 2.174043344305154e - 05$$

this gives

$$\begin{aligned} \frac{1}{2.174043344305154e - 05} &= e^{n \ln(2)} \\ \frac{\ln\left(\frac{1}{2.174043344305154e - 05}\right)}{\ln(2)} &= n \\ n &\sim 16 \end{aligned}$$

OR

$$\begin{aligned} \frac{\ln\left(\frac{1}{1.735377145906103e - 05}\right)}{\ln(2)} &= n \\ n &\sim 16 \end{aligned}$$

5. (30 pts) Consider the linear system ( $Ax = b$ );

$$A = \begin{bmatrix} 1 & 3 & 1 & 1 \\ 2 & 5 & 2 & 2 \\ -1 & -3 & -3 & 5 \\ 1 & 3 & 2 & 2 \end{bmatrix} \quad \text{and} \quad b = \begin{bmatrix} 6 \\ 2 \\ 4 \\ 3 \end{bmatrix}$$

- i Solve this system by Gaussian elimination with pivoting. How many row interchanges are needed?
- ii What is the value of determinant?
- iii Obtain the  $LU$  decomposition of the system.
- iv Repeat without any row interchanges (only for the first item). Do you get the same results? Why?

```

>> A=[1 3 1 1; 2 5 2 2; -1 -3 -3 5; 1 3 2 2]
>> b=[6 2 4 3]
>> format short
>> GEPivShow(A,b')
Begin forward elmination with Augmented system:
    1    3    1    1    6
    2    5    2    2    2
   -1   -3   -3    5    4
    1    3    2    2    3
Swap rows 1 and 2;  new pivot = 2
After elimination in column 1 with pivot = 2.000000
    2.0000    5.0000    2.0000    2.0000    2.0000
         0    0.5000         0         0    5.0000
         0   -0.5000   -2.0000    6.0000    5.0000
         0    0.5000    1.0000    1.0000    2.0000
After elimination in column 2 with pivot = 0.500000
    2.0000    5.0000    2.0000    2.0000    2.0000
         0    0.5000         0         0    5.0000
         0         0   -2.0000    6.0000   10.0000
         0         0    1.0000    1.0000   -3.0000
After elimination in column 3 with pivot = -2.000000
    2.0000    5.0000    2.0000    2.0000    2.0000
         0    0.5000         0         0    5.0000
         0         0   -2.0000    6.0000   10.0000
         0         0         0    4.0000    2.0000

ans =
   -21.0000
    10.0000
    -3.5000
     0.5000
>> det(A)
ans =     8
>> 2.0000*0.5000*-2.0000*4.0000 %product of the diagonal of U
ans =     8
% For LU-decomposition
>> [L,U,pv]=luPiv(A)
L =
    1.0000         0         0         0
    0.5000    1.0000         0         0
   -0.5000   -1.0000    1.0000         0
    0.5000    1.0000   -0.5000    1.0000
U =
    2.0000    5.0000    2.0000    2.0000

```

```

0      0.5000      0      0
0      0      -2.0000      6.0000
0      0      0      4.0000
pv =
    2
    1
    3
    4
% one time pivoting
% solution is completed
%*****
% For proving purpose
>> A=[1 3 1 1; 2 5 2 2; -1 -3 -3 5; 1 3 2 2]
A =

    1    3    1    1
    2    5    2    2
   -1   -3   -3    5
    1    3    2    2
% our Identity matrix becomes for swaping rows 1 and 2
>> pivoting1=[0 1 0 0; 1 0 0 0; 0 0 1 0; 0 0 0 1]
pivoting1 =

    0    1    0    0
    1    0    0    0
    0    0    1    0
    0    0    0    1
% apply this pivoting to our original matrix
>> A=pivoting1*A
A =

    2    5    2    2
    1    3    1    1
   -1   -3   -3    5
    1    3    2    2
>> [L,U,pv] = luPiv(A)

L =

    1.0000      0      0      0
    0.5000     1.0000      0      0
   -0.5000    -1.0000     1.0000      0
    0.5000     1.0000    -0.5000     1.0000

```

U =

2.0000	5.0000	2.0000	2.0000
0	0.5000	0	0
0	0	-2.0000	6.0000
0	0	0	4.0000

pv =

1  
2  
3  
4

% it is proved.

\*\*\*\*\*

% for not pivoting case;

>> GEshow(A,b')

Begin forward elimination with Augmented system:

1	3	1	1	6
2	5	2	2	2
-1	-3	-3	5	4
1	3	2	2	3

After elimination in column 1 with pivot = 1.000000

1	3	1	1	6
0	-1	0	0	-10
0	0	-2	6	10
0	0	1	1	-3

After elimination in column 2 with pivot = -1.000000

1	3	1	1	6
0	-1	0	0	-10
0	0	-2	6	10
0	0	1	1	-3

After elimination in column 3 with pivot = -2.000000

1	3	1	1	6
0	-1	0	0	-10
0	0	-2	6	10
0	0	0	4	2

ans =

-21.0000  
10.0000

```
-3.5000
 0.5000
% Solutions are the same. They are same because the system is
% not ill-conditioned.
```